

SHAFT DESIGN

Use of Shafts

A machine is a device that converts some sort of energy into work. In many machines transfer of power (energy with respect to time) is needed in order to perform this task. Shafts are efficient devices for transferring power and can commonly be found in machines world wide.

Shaft Definitions

Shaft- A rotating member used to transmit power.
Spindle- A short shaft or axle (e.g. head-stock spindle of a lathe).
Stub shaft- A shaft that is integral with a motor, engine or prime mover and is of a size, shape, and projection as to permit easy connection to other shafts

Line shaft- A shaft connected to a prime mover and used to transmit power to one or several machines
Jackshaft- (Sometimes called countershaft) A short shaft that connects a prime mover with a line shaft and a machine

Flexible shaft- A connector which permits transmission of motion between two members whose axes are at an angle with each other

Most shafts are round but they can come in many different shapes including square and octagonal. Keys and notches can also result in some unique shapes.

Hollow shafts are lighter than solid shafts of comparable length but are more expensive to manufacture. Thusly hollow shafts are primarily only used when weight is critical. For example the propeller shafts on rear wheel drive cars require lightweight shafts in order to handle stresses within the operating range of the vehicle.

General Principles

Keys, splines, short shaft bearings close to the applied loads. This will reduce deflections and bending moments, and increases critical speeds.

Place necessary stress raisers away from highly stressed shaft regions if possible. If unavoidable, use generous radii and good surface finishes. Consider local surface-strengthening processes (shot-peening or cold-rolling).

Use inexpensive steels for deflection-critical shafts because all steels have essentially the same modulus of elasticity.

Early in the design of any given shaft, an estimate is usually made of whether strength or deflection will be the critical factor. A preliminary design is based on that criterion. After the remaining factor is checked.

Material Processing Tips

To resist wear, case-hardening methods such as nitriding, cyaniding, flame and induction hardening can be used.

Cold-drawn shafts have better physical properties than hot-rolled bars of similar steels. Cold-drawing causes residual surface stresses that offset higher endurance strength due to hot-rolling.

Cuttings, keyways and slots in the shaft may cause warping due to the relief of surface stresses. Peening and other processes that produce surface compressive stresses counteract the effect of fatigue stresses.

Shaft Equations:

All of the following equations are general equations; you may need to use modifying factors such as: loading factors, pulsating power source factors, safety factors, and stress concentration factors.

Basic equations in torsion:
 Solid round shaft:

$$\tau = \frac{16 \cdot T}{\pi \cdot D^3}$$

Hollow round shaft:

$$\tau = \frac{16 \cdot T \cdot D_o}{\pi \cdot (D_o^4 - D_i^4)}$$

Basic equation in bending:
 Solid shaft:

$$\sigma = \frac{32 \cdot M}{\pi \cdot D^3}$$

Hollow shaft:

$$\sigma = \frac{32 \cdot M \cdot D_o}{\pi \cdot (D_o^4 - D_i^4)}$$

Combined loading (axial + shear):

$$\tau_{max} = \frac{2}{\pi \cdot D^2} \cdot \sqrt{(8 \cdot M + F \cdot D)^2 + (8 \cdot T)^2}$$

(8-4) max shear stress ↑

$$\sigma' = \frac{4}{\pi \cdot D} \cdot \sqrt{(8 \cdot M + F \cdot D)^2 + 48 \cdot T^2}$$

(8-5) von Mises stress / Torsional deflection:

$$\theta = \frac{32 \cdot T \cdot L}{\pi \cdot G \cdot D^4}$$

Radious
 Factors of Safety:

$$\tau_w = \frac{S}{2 \cdot n}$$

(8-6) Max shear stress theory ↑

$$\sigma' = \frac{S}{n}$$

(8-7) Distortion energy

T = Torque (lb-in, N-m)
 F = axial load (lb, N)

S = yield strength
 n = factor of safety

D = diameter of solid shaft (in, m)
 D_o = outside diameter of solid shaft (in, m)

D_i = inside diameter of solid shaft (in, m)
 M = bending moment (lb-in, N-m)

L = length of shaft (in, m)
 G = shear modulus (psi, Pa)

Rules of Deflection

Deflections should not cause mating gear teeth to separate more than about .005 in. They should also not cause the relative slope of the gear axes to change more than .001 deg.

The shaft stiffness across a plain bearing must be small compared to the film thickness.

The shaft angular deflection at a ball or roller bearing should generally not exceed .04 deg unless the bearing is self-aligning.

Rule Of Thumb: Restrict the torsional displacement for every 20 diameters of length, sometimes less.

Rule Of Thumb: In bending the deflection should be limited to .01 in. per foot of length between supports.

Common Elements Used To Transfer Torque

- Keys
- Pins
- Splines
- Press or shrink fits
- Screws
- Tapered fits

Common Means of Securing Shafts

- Press and shrink fits
- Cotter and washer
- Nut and washer
- Sleeve
- Shaft shoulder
- Pins

Common Shaft Sizes

Common Shaft Sizes (English in.)		Common Shaft Sizes (Metric mm)	
1/2	1.778	5	50.8
5/8	1.575	6	60.0
3/4	1.915	8	80.0
7/8	2.255	10	100.0
1	2.595	12	120.0
1 1/8	3.275	14	140.0
1 1/4	3.615	16	160.0
1 3/8	3.955	18	180.0
1 1/2	4.635	20	200.0
1 5/8	4.975	25	250.0
1 3/4	5.315	30	300.0
1 7/8	5.655	35	350.0
2	6.295	40	400.0
2 1/8	6.635	45	450.0
2 1/4	6.975	50	500.0
2 3/8	7.315	55	550.0
2 1/2	7.995	60	600.0
2 5/8	8.335	65	650.0
2 3/4	8.675	70	700.0
2 7/8	9.015	75	750.0
3	9.655	80	800.0
3 1/8	9.995	85	850.0
3 1/4	10.335	90	900.0
3 3/8	10.675	95	950.0
3 1/2	11.315	100	1000.0
3 5/8	11.655	105	1050.0
3 3/4	11.995	110	1100.0
3 7/8	12.335	115	1150.0
4	12.975	120	1200.0

* It is advisable to consult the supplier for the availability of desired shaft sizes



www.shafthasa.com/shafts.html

REFERENCE:
 H. J. Shigley, Joseph E. Mischke, and Charles R. Mischke,
 Mechanical Engineering Design, Fifth Edition, McGraw-Hill, 2002.

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 AUSTIN HOWARD
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 ERIK VAN PATTEN